

GauGAN/SPADE

Semantic Image Synthesis with Spatially Adaptive Normalization

Ming-Yu Liu

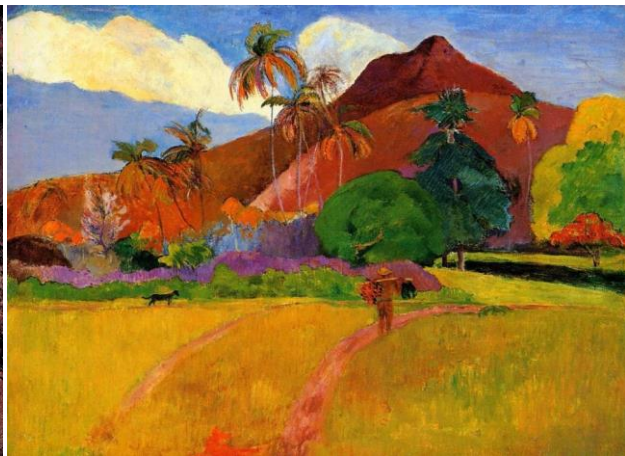
NVIDIA



Image credit: <https://www.smithsonianmag.com/history/journey-oldest-cave-paintings-world-180957685/>



Cave painting



By Gauguin



By fabulouswalrus
using MS Paint



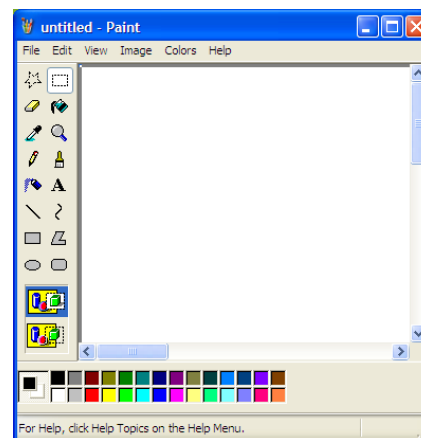
By Pablo Munoz Gomez
using NVIDIA GauGAN



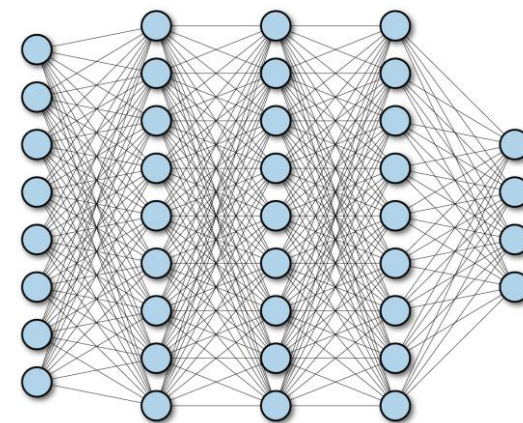
Rock



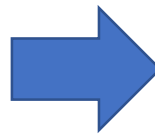
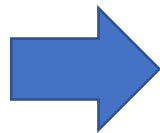
Brush



Digital revolution

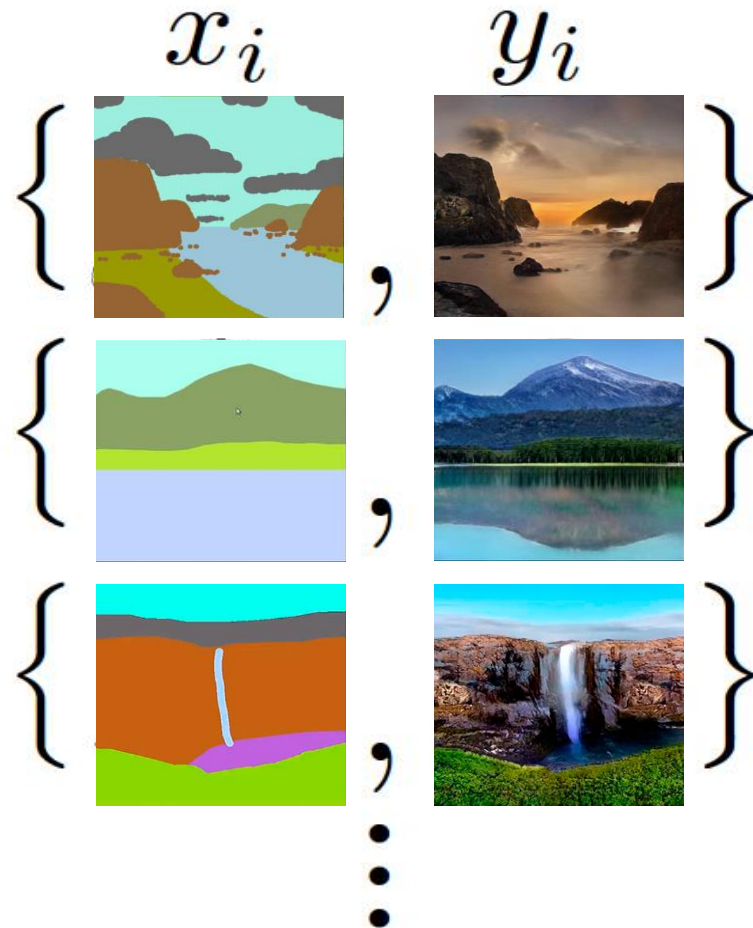


AI revolution

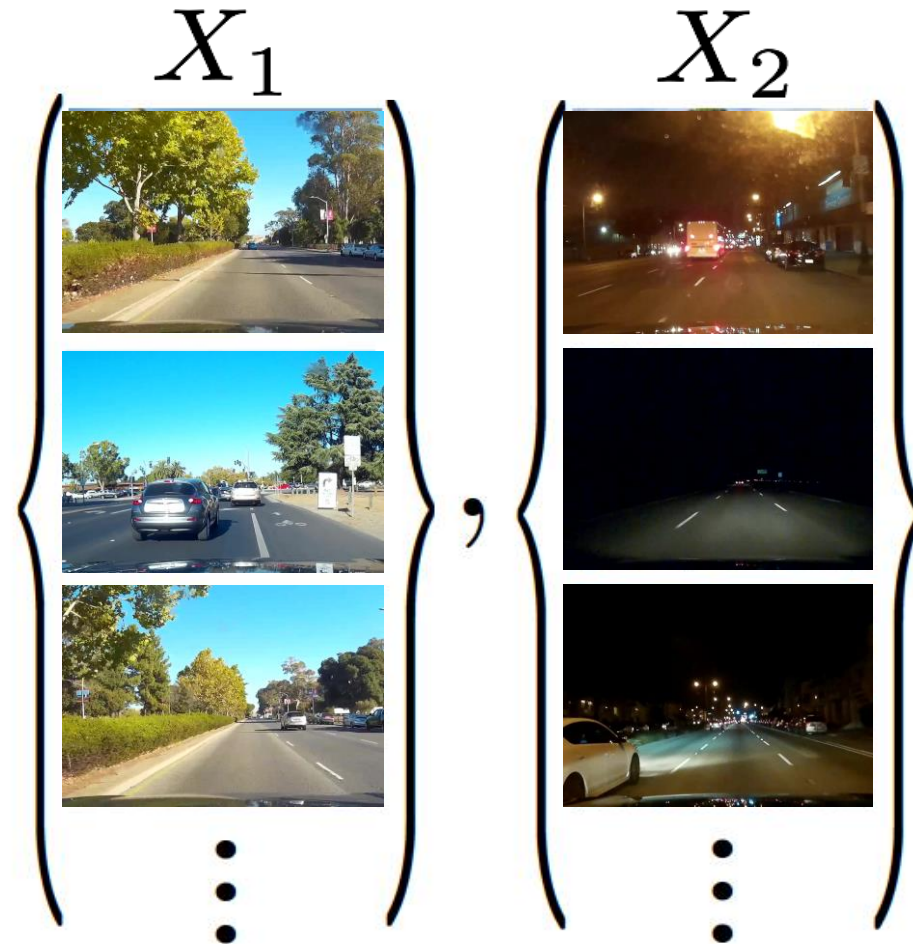


Supervised vs Unsupervised

Supervised/Paired/Aligned/Registered

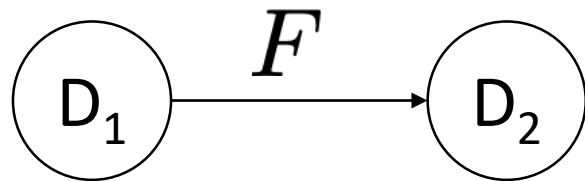


Unsupervised/Unpaired/Unaligned/Unregistered



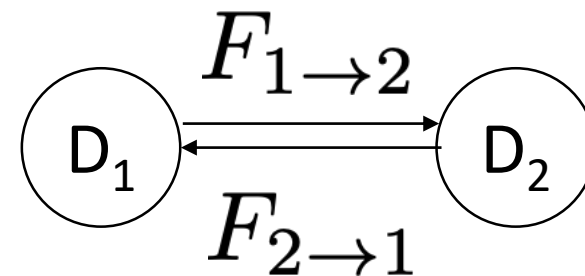
- Supervised/Paired/Aligned/Registered






- Image Analogy (Hertzmann et. al. 2001)
- pix2pix (Isola et. al. 2017)
- CRN (Chen et. al. 2017)
- BicycleGAN (Zhu et. al. 2017)
- pix2pixHD (Wang et. al. 2018)
- SIMS (Qi et. al. 2018)
- SPADE (Park et. al. 2019)
- ...



- Unsupervised/Unpaired/Unaligned/Unregistered

- CoupledGAN (Liu et. al. 2016)
- DTN (Taigman et. al. 2017)
- DiscoGAN (Kim et. al. 2017)
- CycleGAN (Zhu et. al. 2017)
- SimGAN (Shrivastava et. al. 2017)
- DualGAN (Yi et. al. 2017)
- UNIT (Liu et. al. 2017)
- MUNIT, 2018 (Huang et. al. 2018)
- DRIT (Lee et. al. 2018)
- XGAN (Royer et. al. 2018)
- GANimorph (Gokaslan et. al. 2018)
- OST (Benaim et. al. 2018)
- FUNIT (Liu et. al. 2019)
- ...

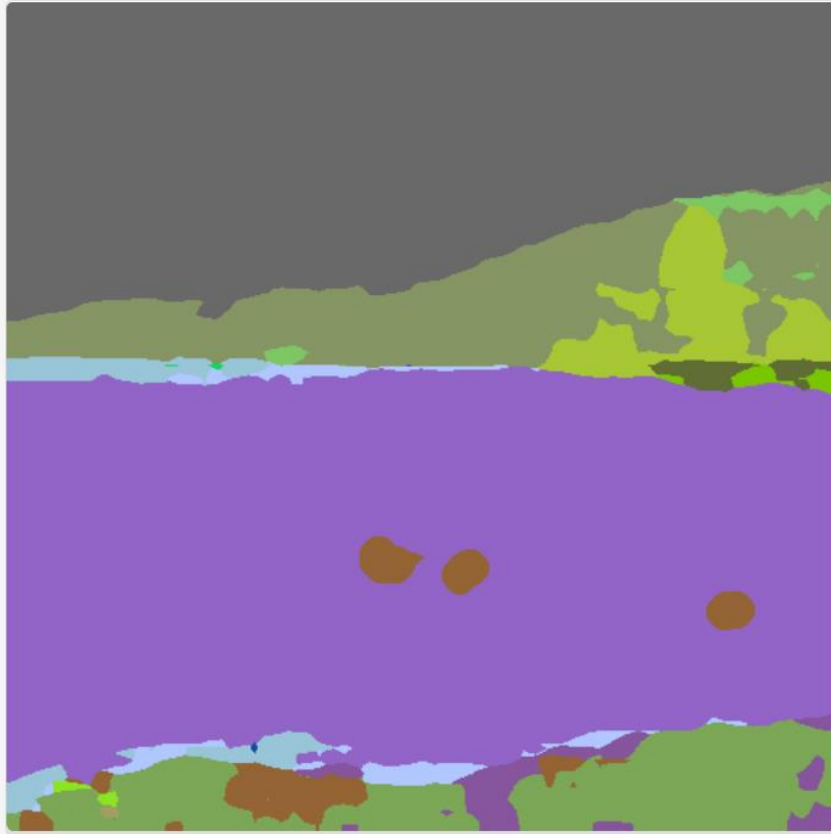


Fill/brush color:  Brush shape:    Brush size: 22 



GauGAN Beta

- Bush
- Cloud
- Dirt
- Grass
- Gravel
- Hill
- Mountain
- Plant
- River
- Road
- Rock**
- Sand
- Sea
- Sky
- Snow
- Stone
- Tree
- Water





@Soerenpepp



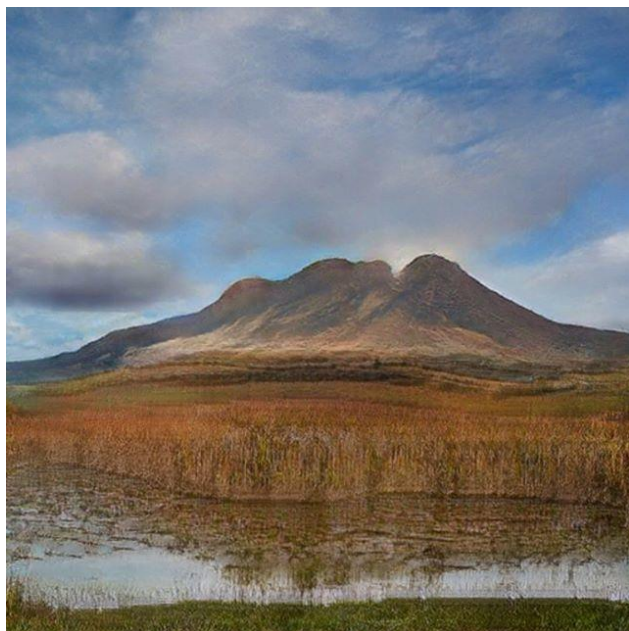
@jonathanfly



@torans_photo123



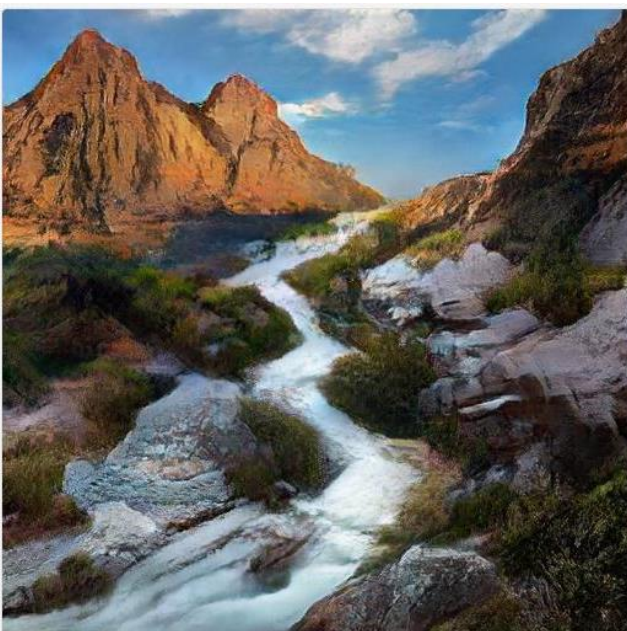
@inning0



@frasSmith



@seahcb



@LipComeralla



Tyler Schatz



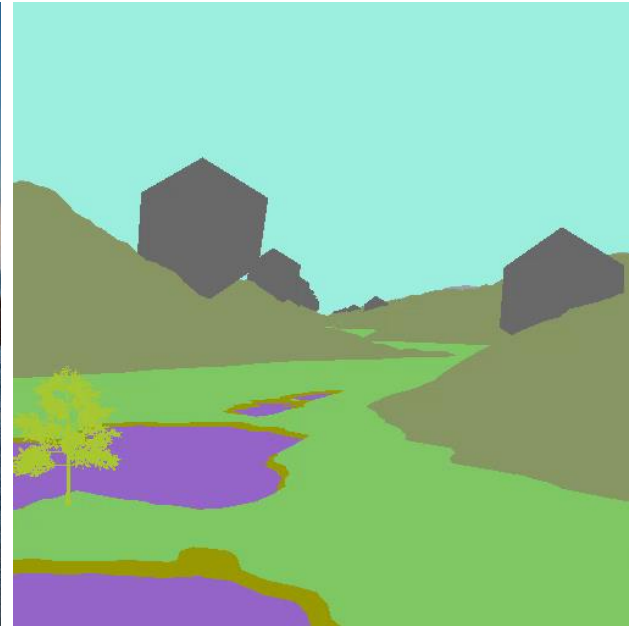
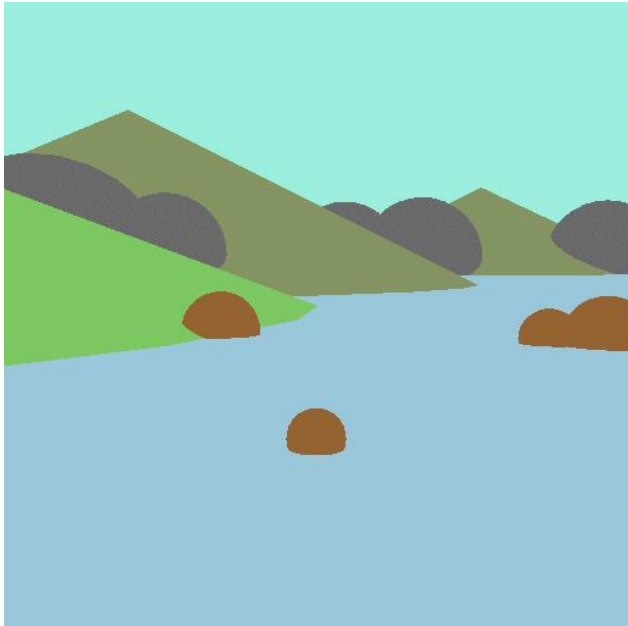
@coliewertz



@darekzabrocki



AI generated image

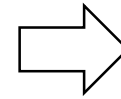
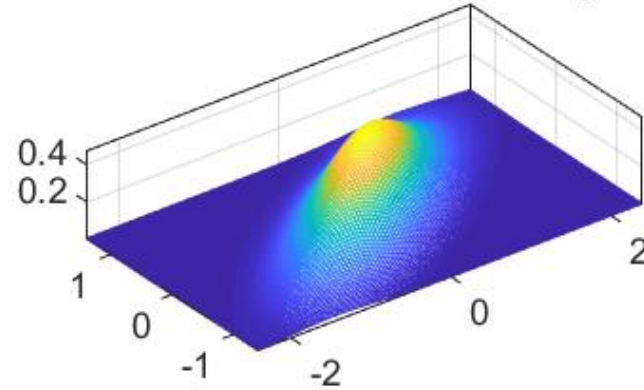
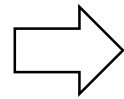
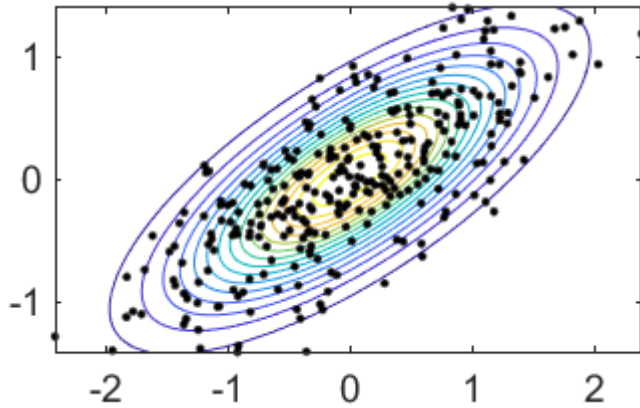


By Jay Axe

By Neil Bickford

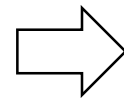
How we achieve it?

Deep Generative Modeling

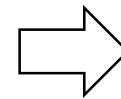
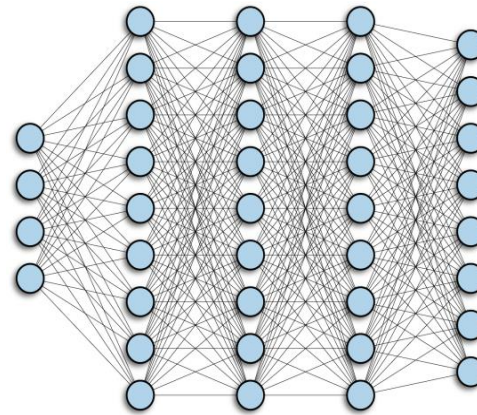


Generate new 2D
Gaussian samples

$$f(x|\mu, \Sigma) = \frac{1}{\sqrt{(2\pi)^d \det(\Sigma)}} \exp\left(-\frac{(x-\mu)^T \Sigma^{-1} (x-\mu)}{2}\right)$$

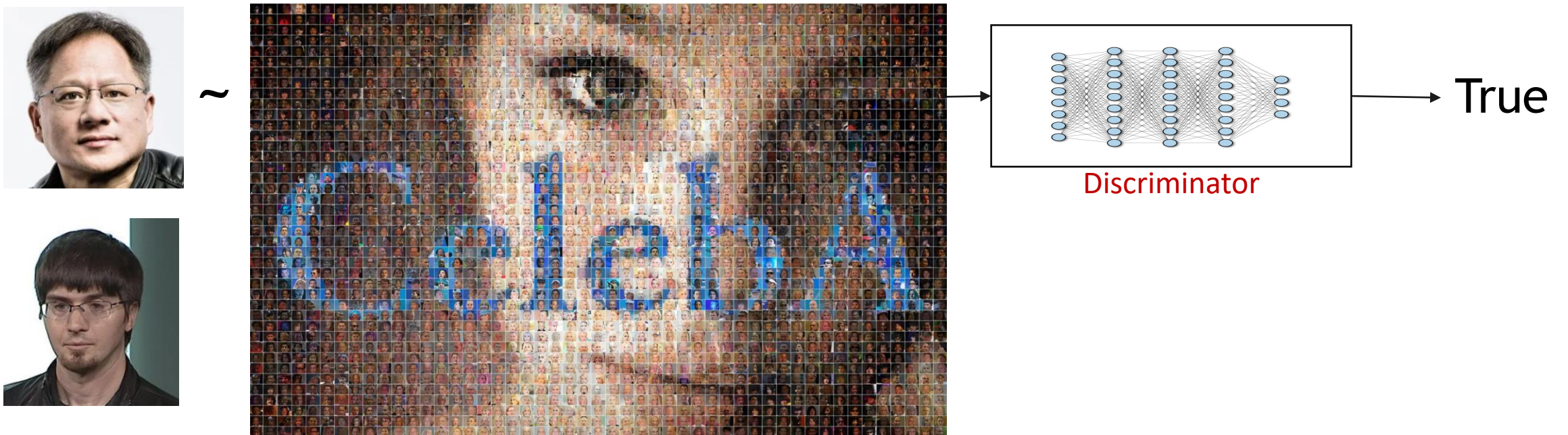
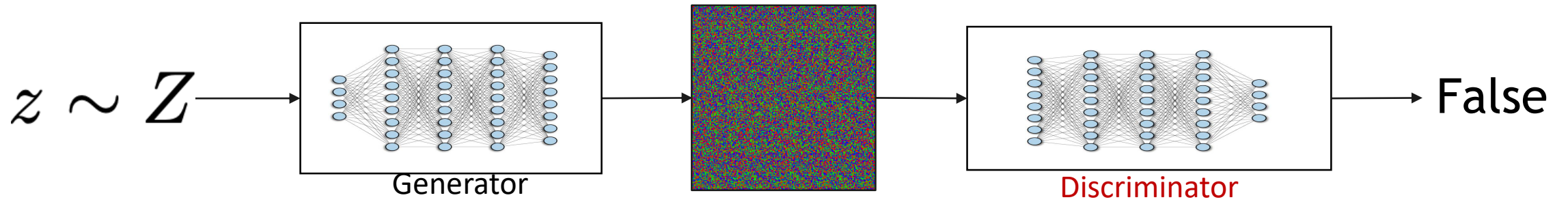


$$f(z) = \frac{1}{2\pi^2} e^{-\frac{z^2}{2}}$$



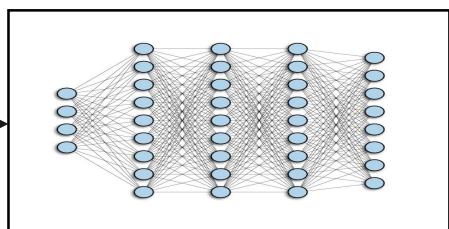
Generate new
images

Generative Adversarial Networks



After training the model for a while

z_1, z_2, z_3, \dots



Generator



Conditional Generative Adversarial Networks

modeling

$$p_{X|Y}$$

sampling

$$z \sim Z, y \sim Y$$

Segmentation Mask–Conditional GANs

$$z \sim Z, y_1 \sim Y$$



$$z \sim Z, y_2 \sim Y$$



$$z \sim Z, y_3 \sim Y$$

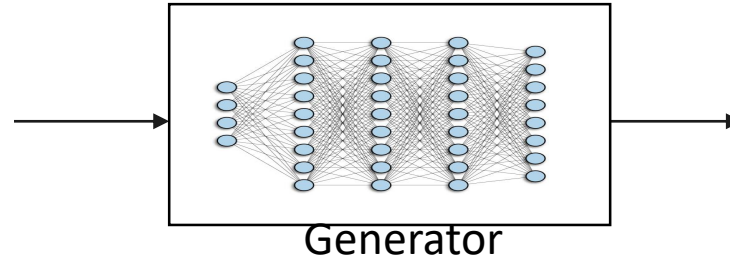
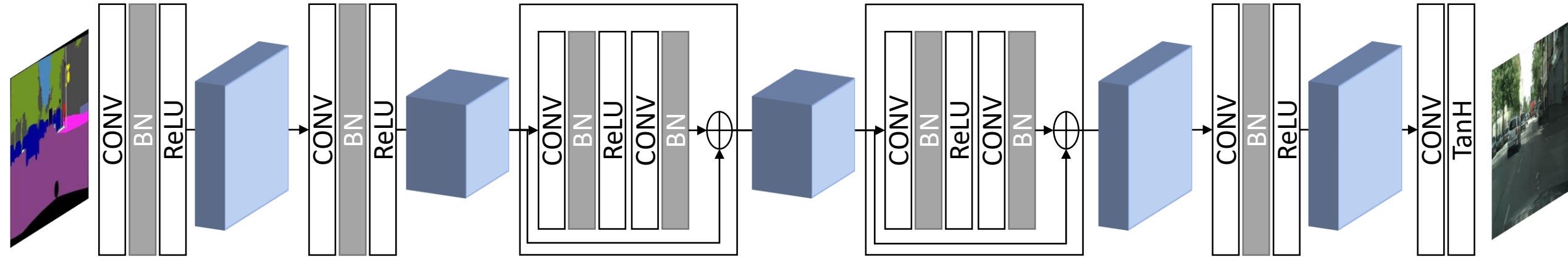


Illustration of pix2pixHD Generator Design



- Previous SOTA method for GAN-based semantic image synthesis
- ResNet-based encoder—decoder architecture
- Work nicely only on highly constrained scenes
- Utilize BatchNorm (BN) or InstanceNorm (IN) in the generator

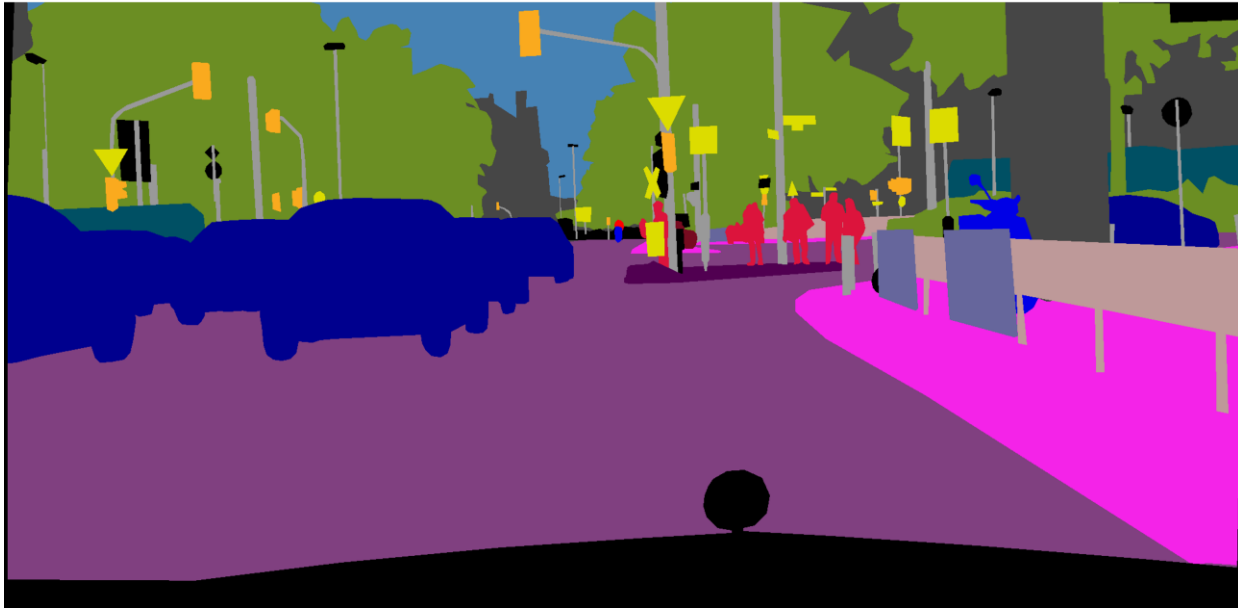
[pix2pixHD: High-Resolution Image Synthesis and Semantic Manipulation with Conditional GANs](#)

Ting-Chun Wang, Ming-Yu Liu, Jun-Yan Zhu, Andrew Tao, Jan Kautz, Bryan Catanzaro

Conference on Computer Vision and Pattern Recognition (CVPR) Oral 2018, Salt Lake City, Utah

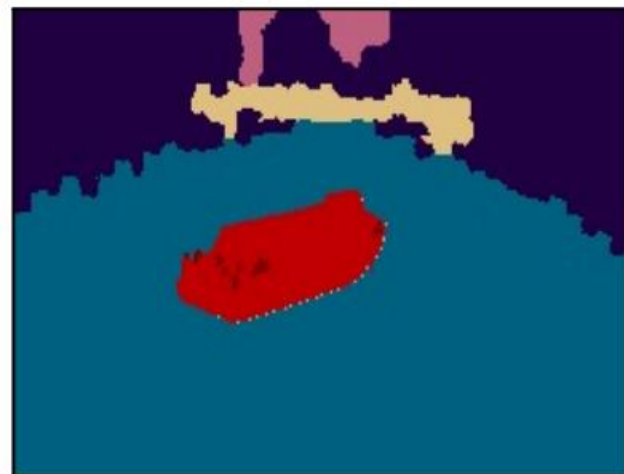
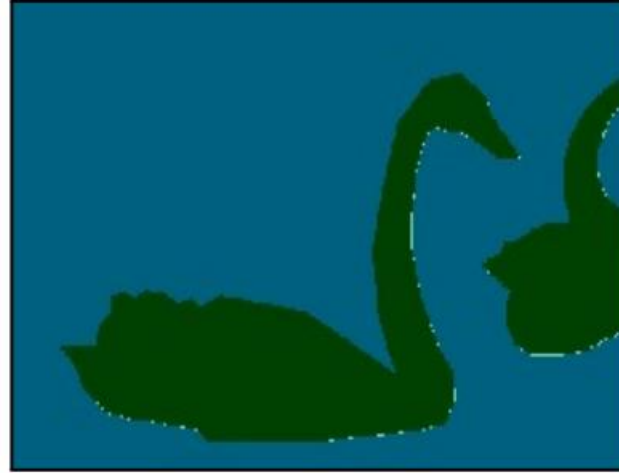
pix2pixHD results

Input labels

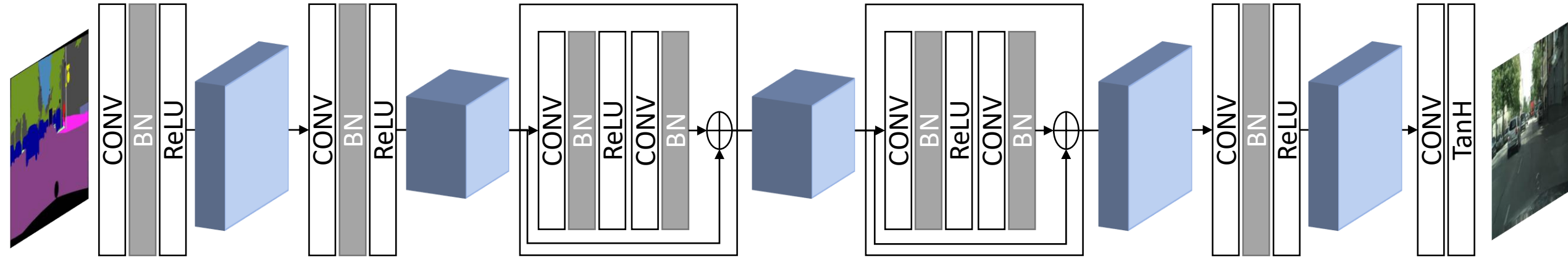


Synthesized image





BN: Batch Normalization



$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_c^{(l)} \frac{h_{n,c,y,x}^{(l)} - \mu_c^{(l)}}{\sigma_c^{(l)}} + \beta_c^{(l)}$$

$$\mu_c^{(l)} = \frac{1}{NHW} \sum_{n,y,x} h_{n,c,y,x}^{(l)}$$

$$\sigma_c^{(l)} = \left(\frac{1}{NHW} \sum_{n,y,x} (h_{n,c,y,x}^{(l)})^2 \right) - \mu_c^{(l)^2}$$

Batch Normalization: Accelerating Deep Network Training by Reducing Internal Covariate Shift

Sergey Ioffe, Christian Szegedy

International Conference on Machine Learning (ICML) 2015, Lille, France,

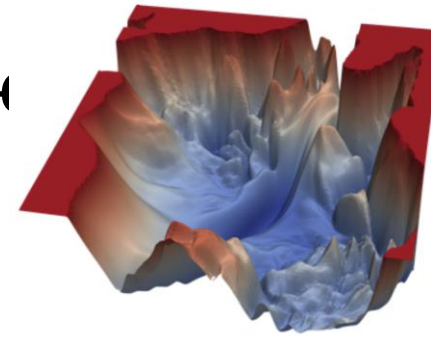
Why Batch Normalization?

- Initial hypothesis: reducing covariance shift in internal activations

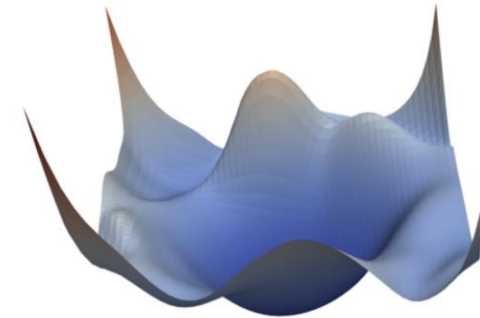
Why Batch Normalization?

- ~~Initial hypothesis: reducing covariance shift in internal activations~~
- New hypothesis #1: leading to smoother optimization landscape
- New hypothesis #2: leading to length-direction decoupling of the weight space -> faster convergence rate

Loss landscape illustration

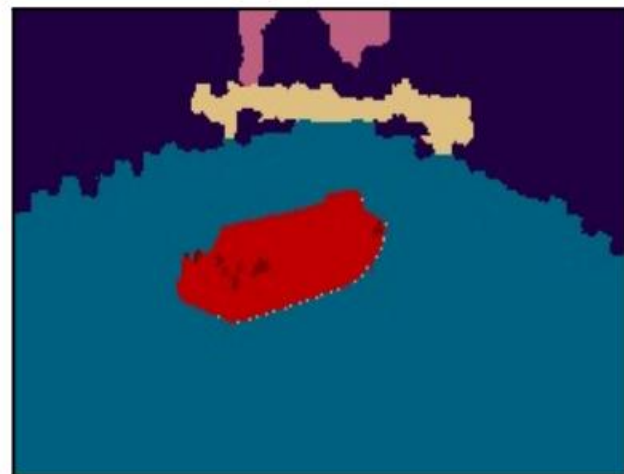
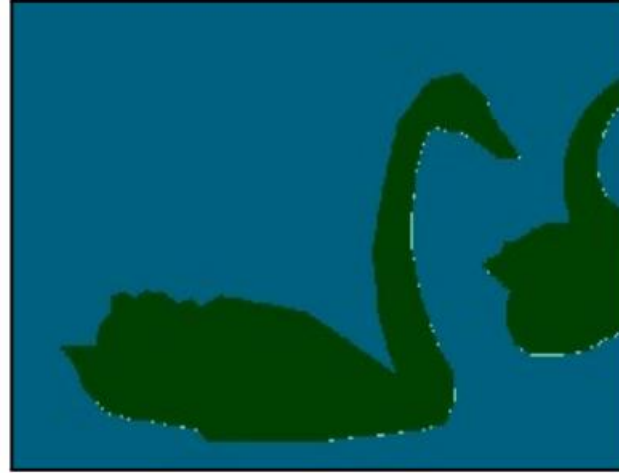


Without BN



With BN

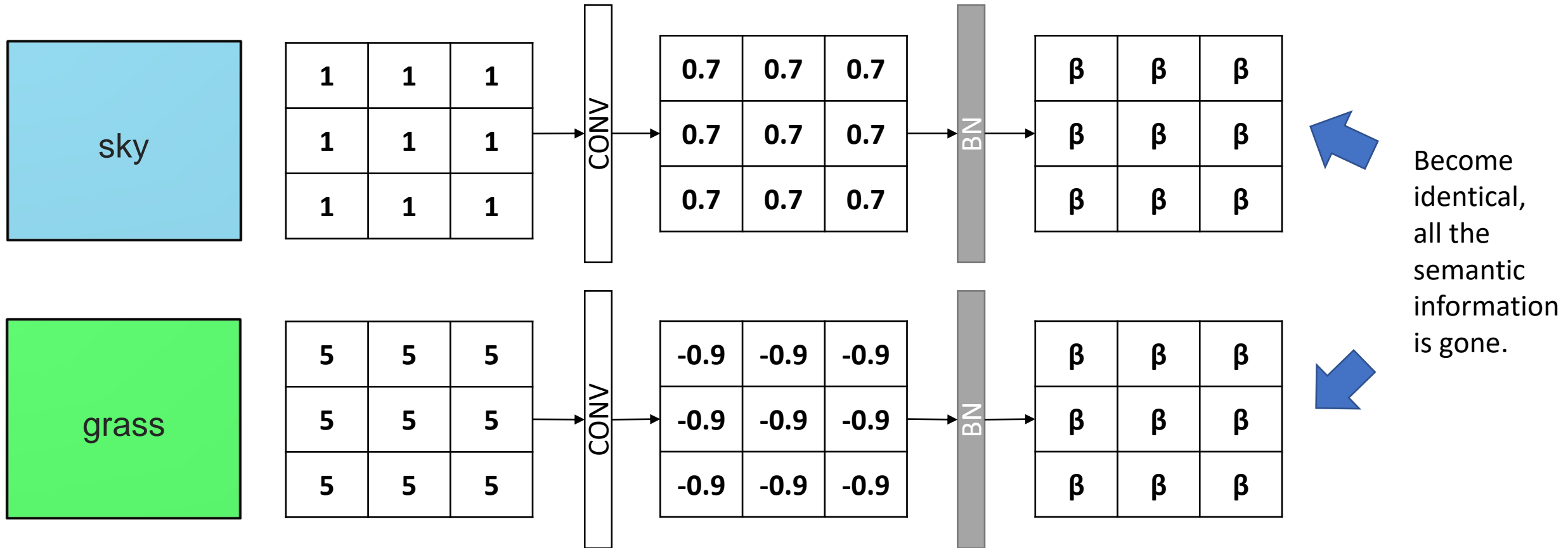
$$\tilde{w} = \underbrace{\gamma}_{\text{length}} \underbrace{\frac{w}{\|w\|_s}}_{\text{direction}}$$



Issue with using Batch Normalization for Semantic Image Synthesis

- It tends to wash away semantic input information.

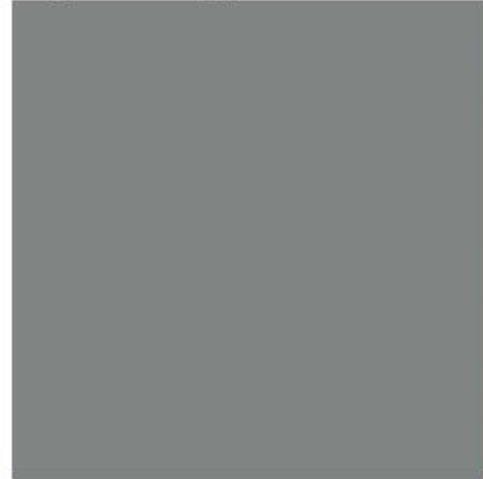
$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_c^{(l)} \frac{h_{n,c,y,x}^{(l)} - \mu_c^{(l)}}{\sigma_c^{(l)}} + \beta_c^{(l)}$$



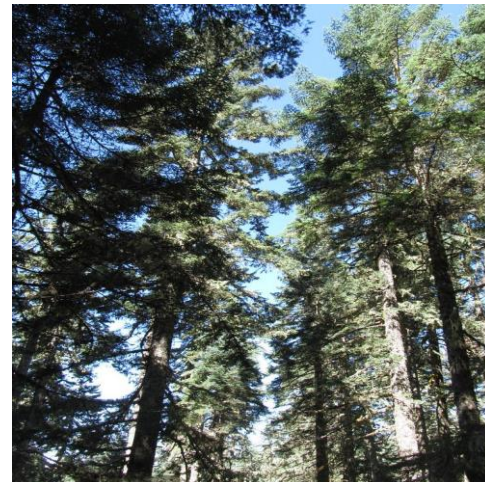
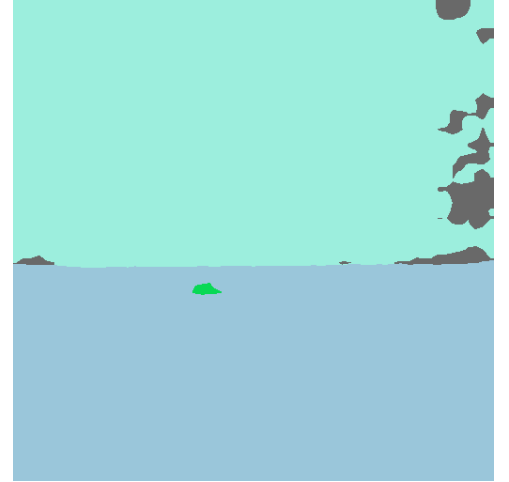
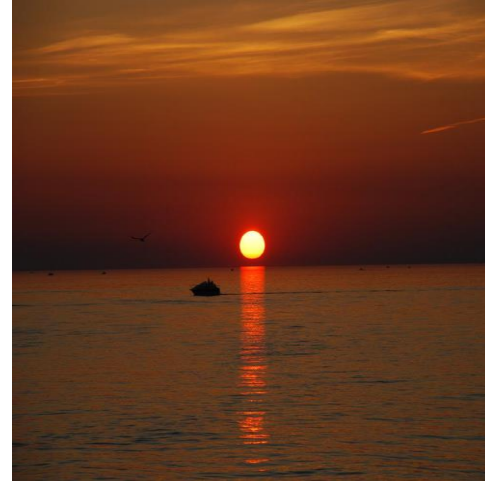
input

pix2pixHD

SPADE



Segmentation masks often contains large uniform regions



SPADE: SPatially Adaptive DEnormalization

BN
$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_c^{(l)} \frac{h_{n,c,y,x}^{(l)} - \mu^{(l)}}{\sigma_c^{(l)}} + \beta_c^{(l)}$$

SPADE
$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_{c,y,x}^{(l)}(s) \frac{h_{n,c,y,x}^{(l)} - \mu^{(l)}}{\sigma_c^{(l)}} + \beta_{c,y,x}^{(l)}(s)$$

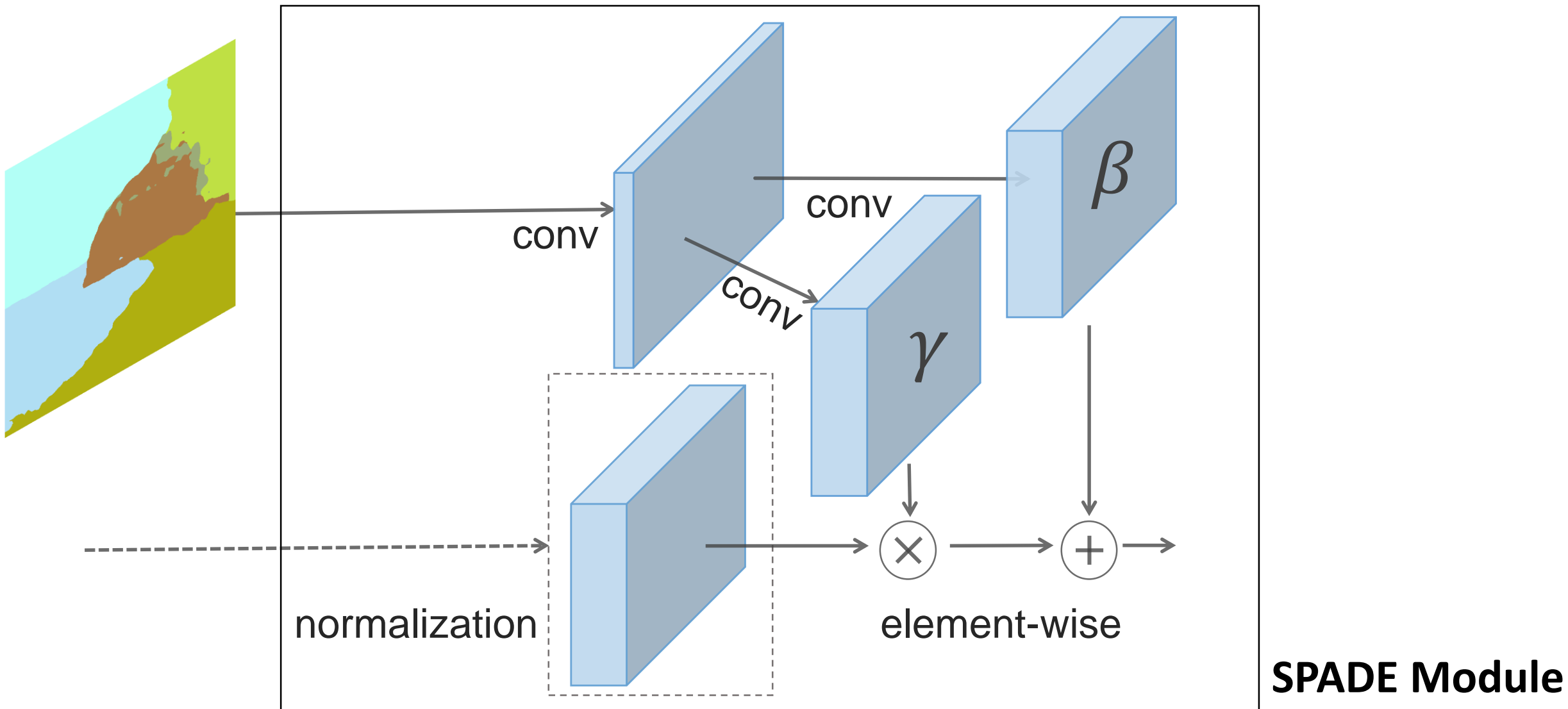
Spatially varying quantity

Depending on the input segmentation mask s

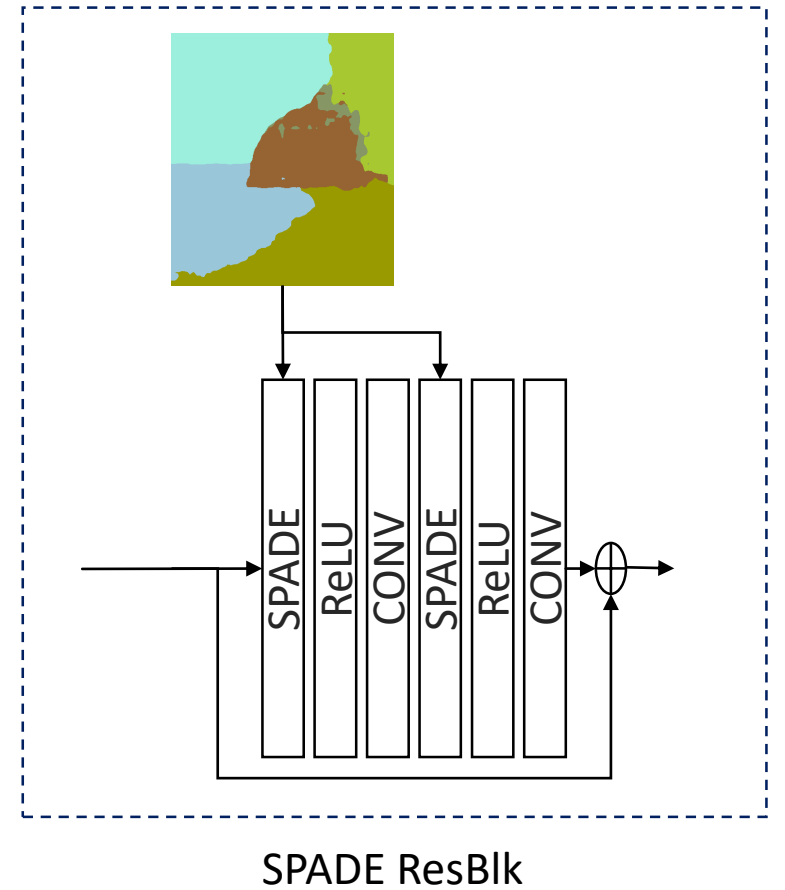
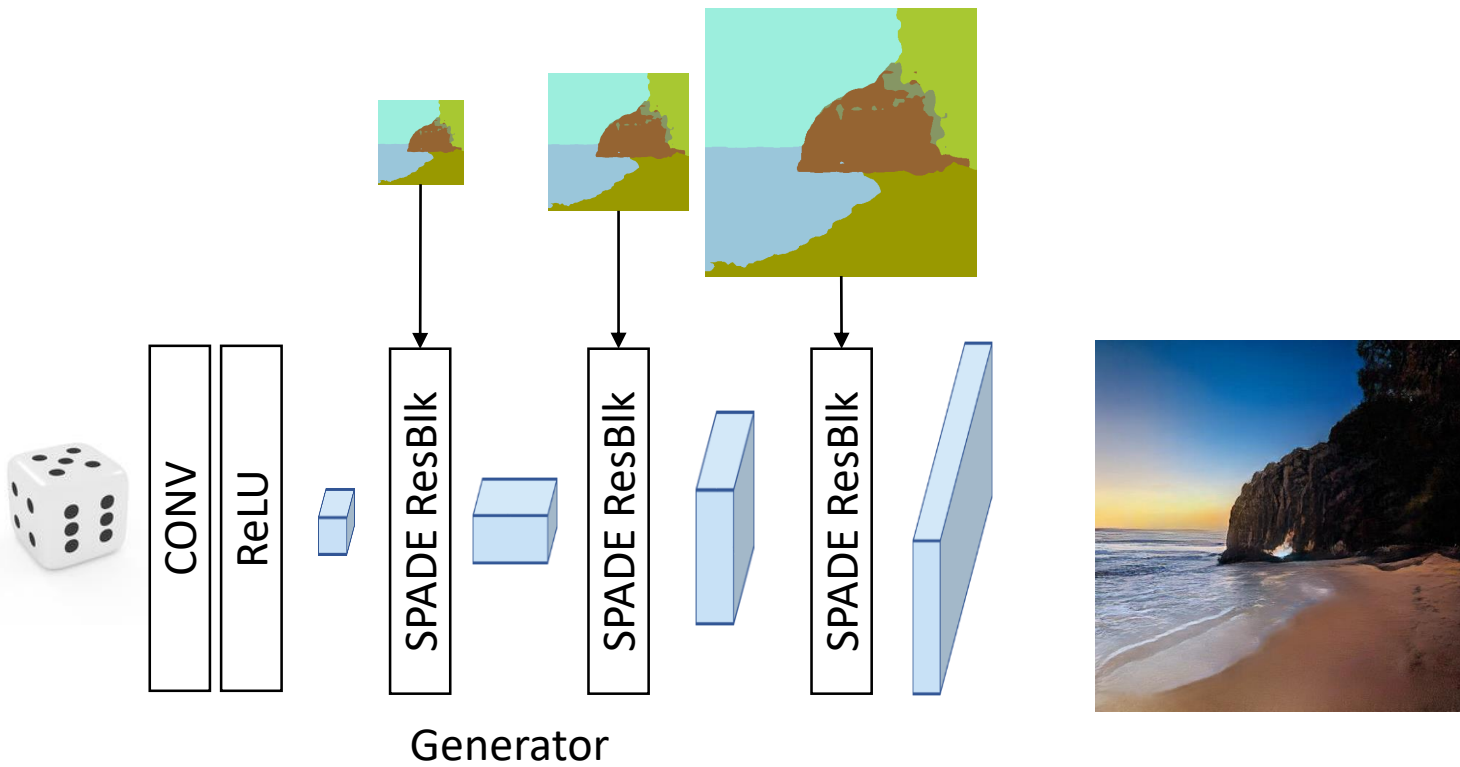
Information removed by normalization can be added back by gamma and beta

SPADE

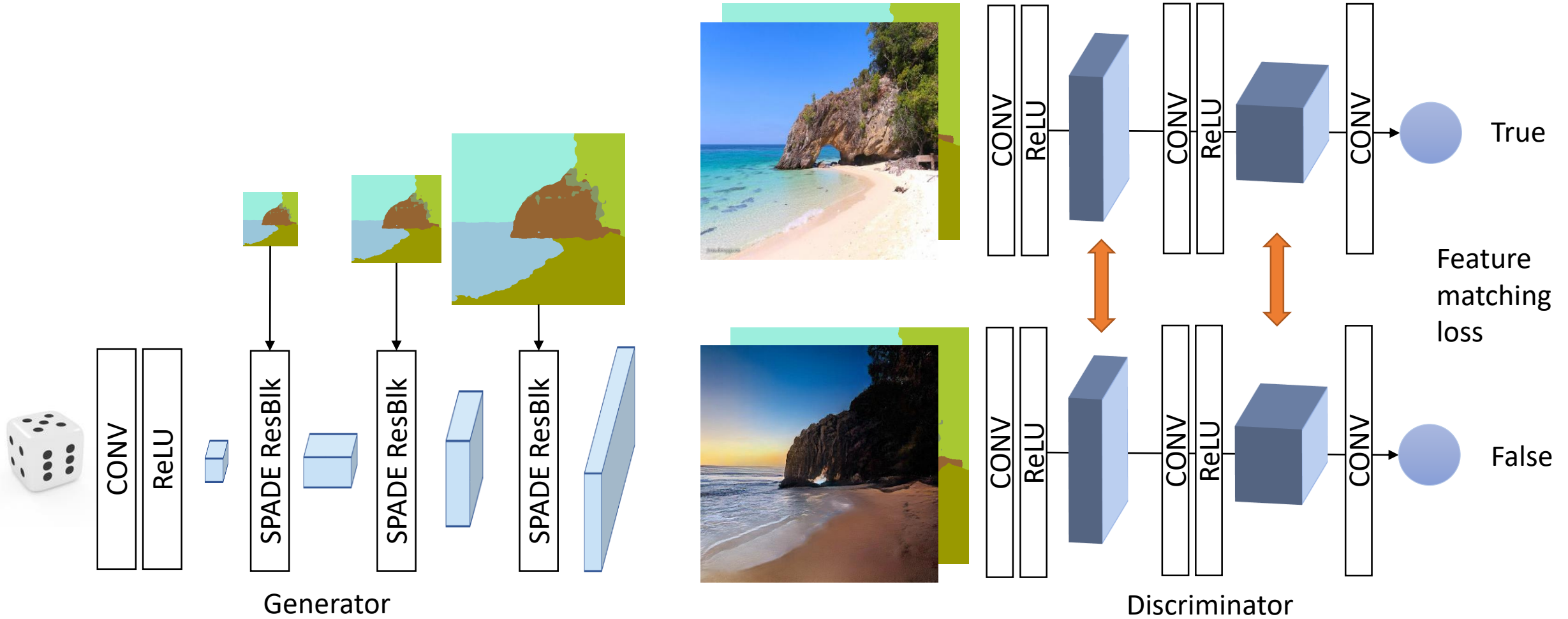
$$\tilde{h}_{n,c,y,x}^{(l)} = \gamma_{c,y,x}^{(l)}(s) \frac{h_{n,c,y,x}^{(l)} - \mu^{(l)}}{\sigma_c^{(l)}} + \beta_{c,y,x}^{(l)}(s)$$



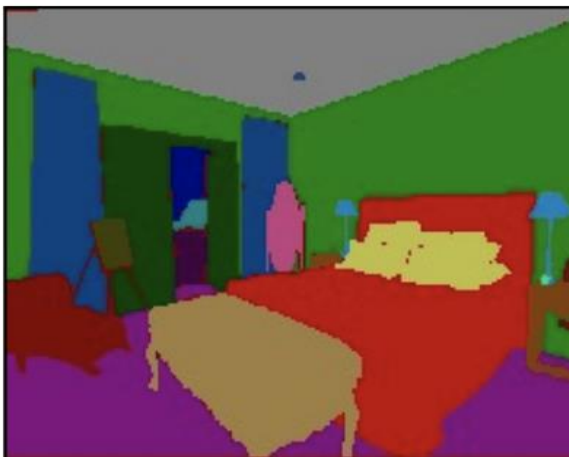
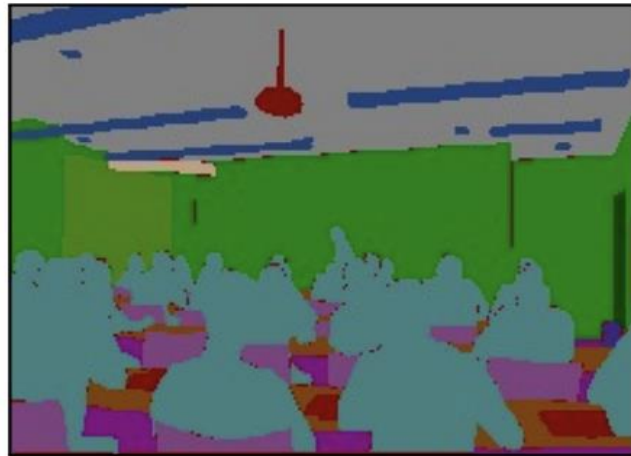
SPADE-based Generator

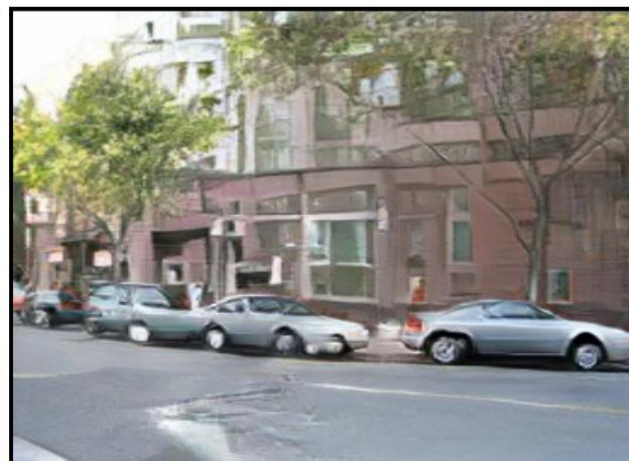
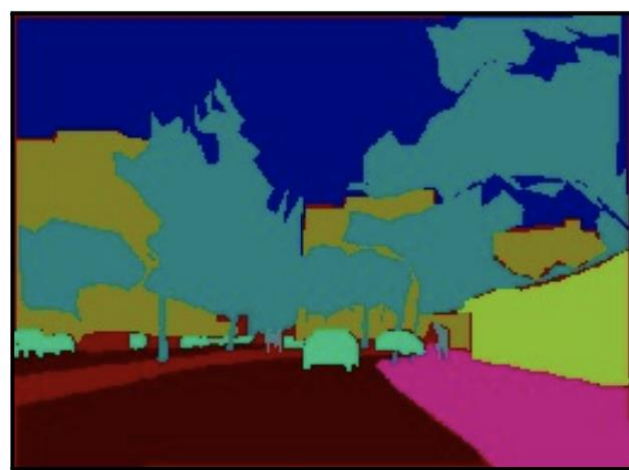
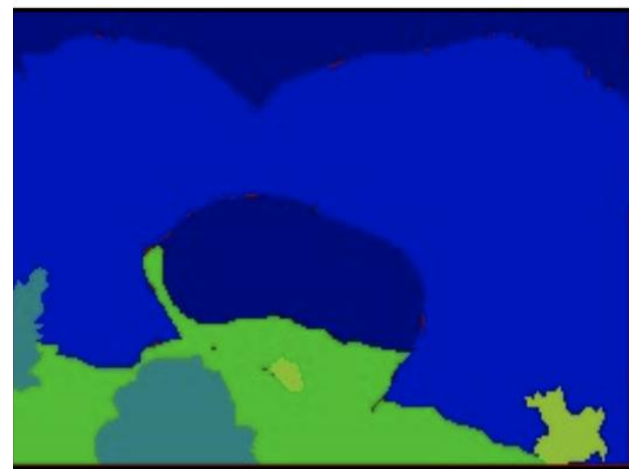


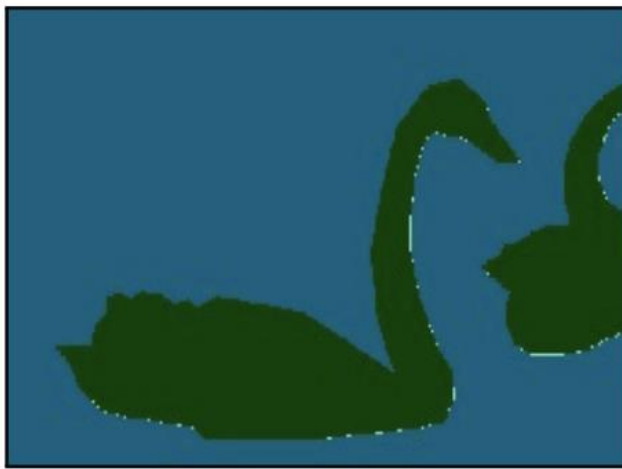
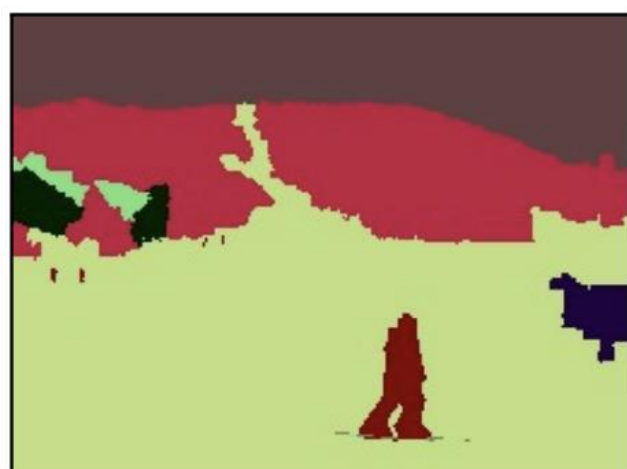
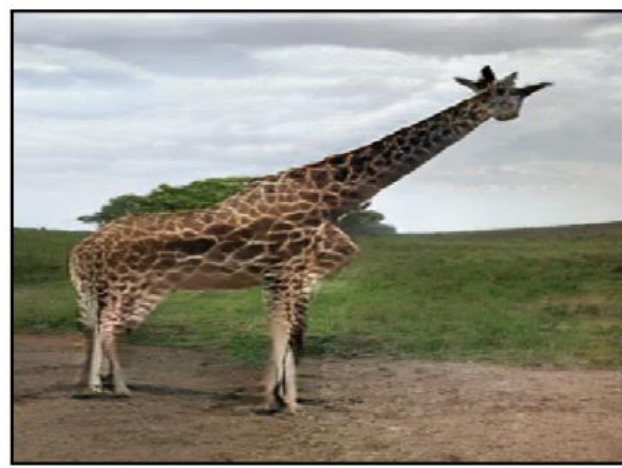
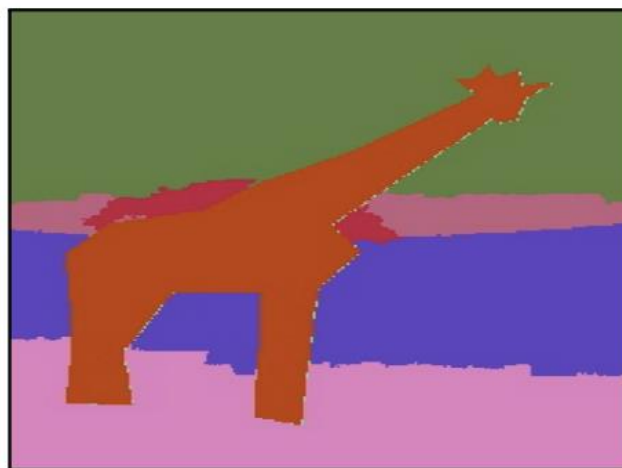
GauGAN Framework



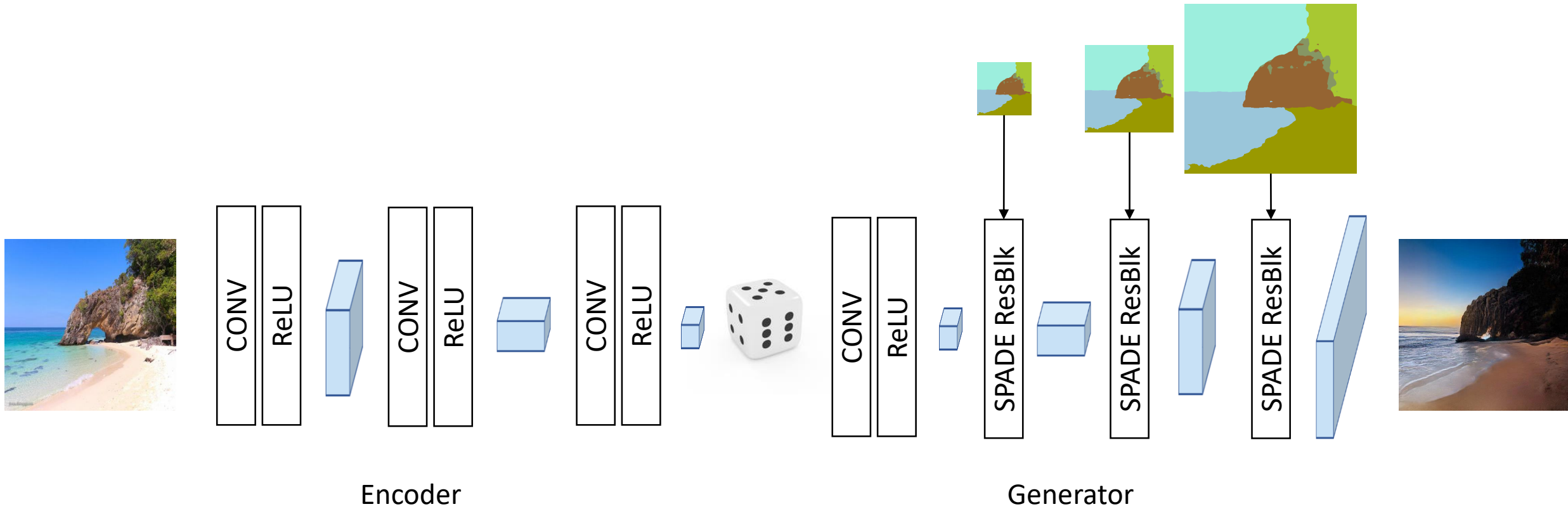
Results



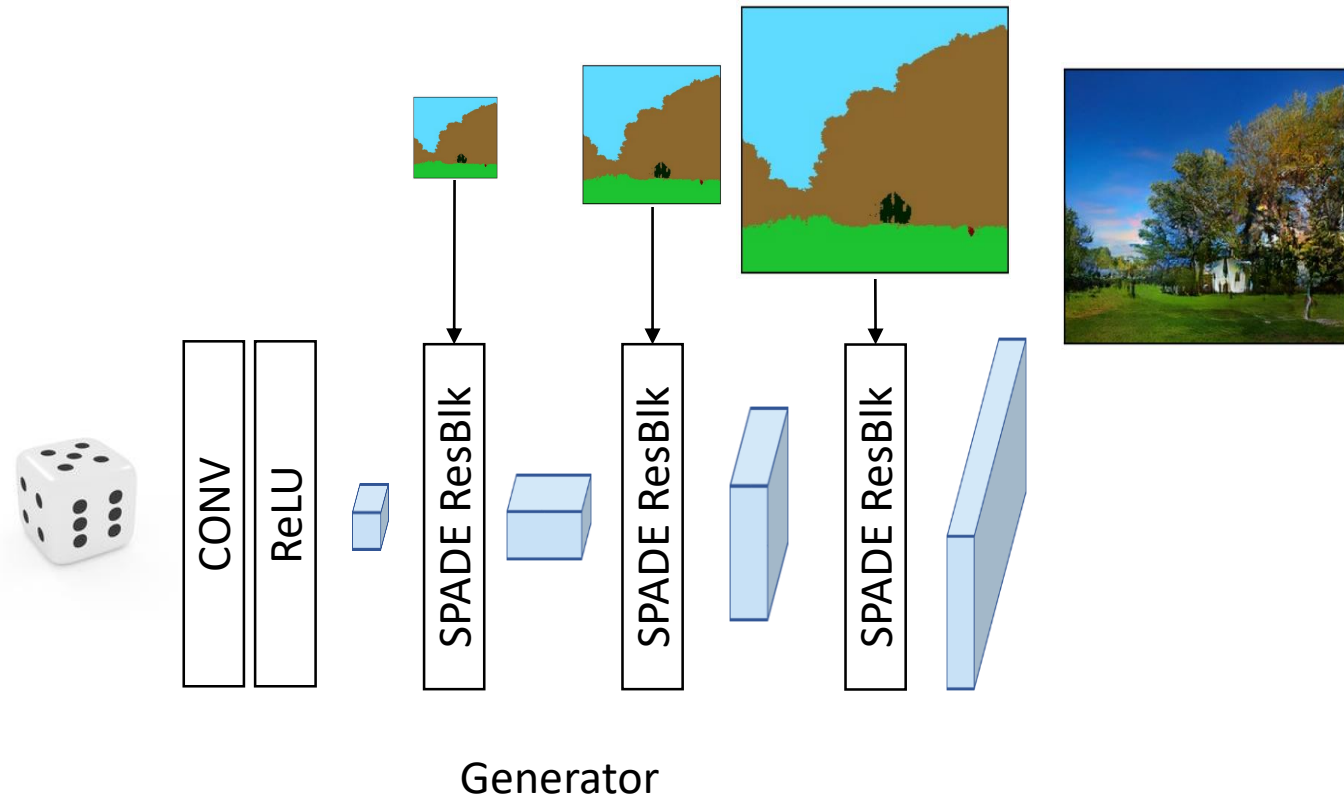




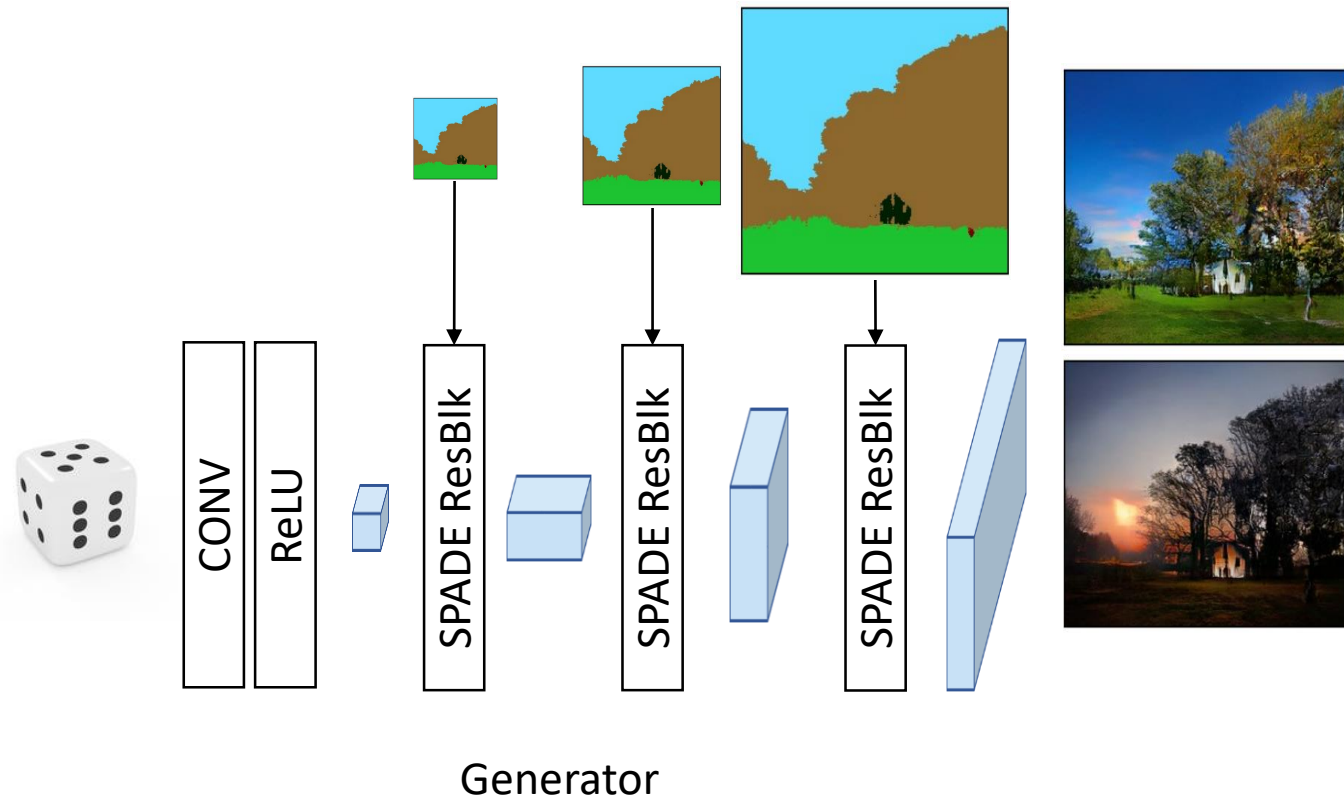
Style Control Learning via a Variational Learning Framework



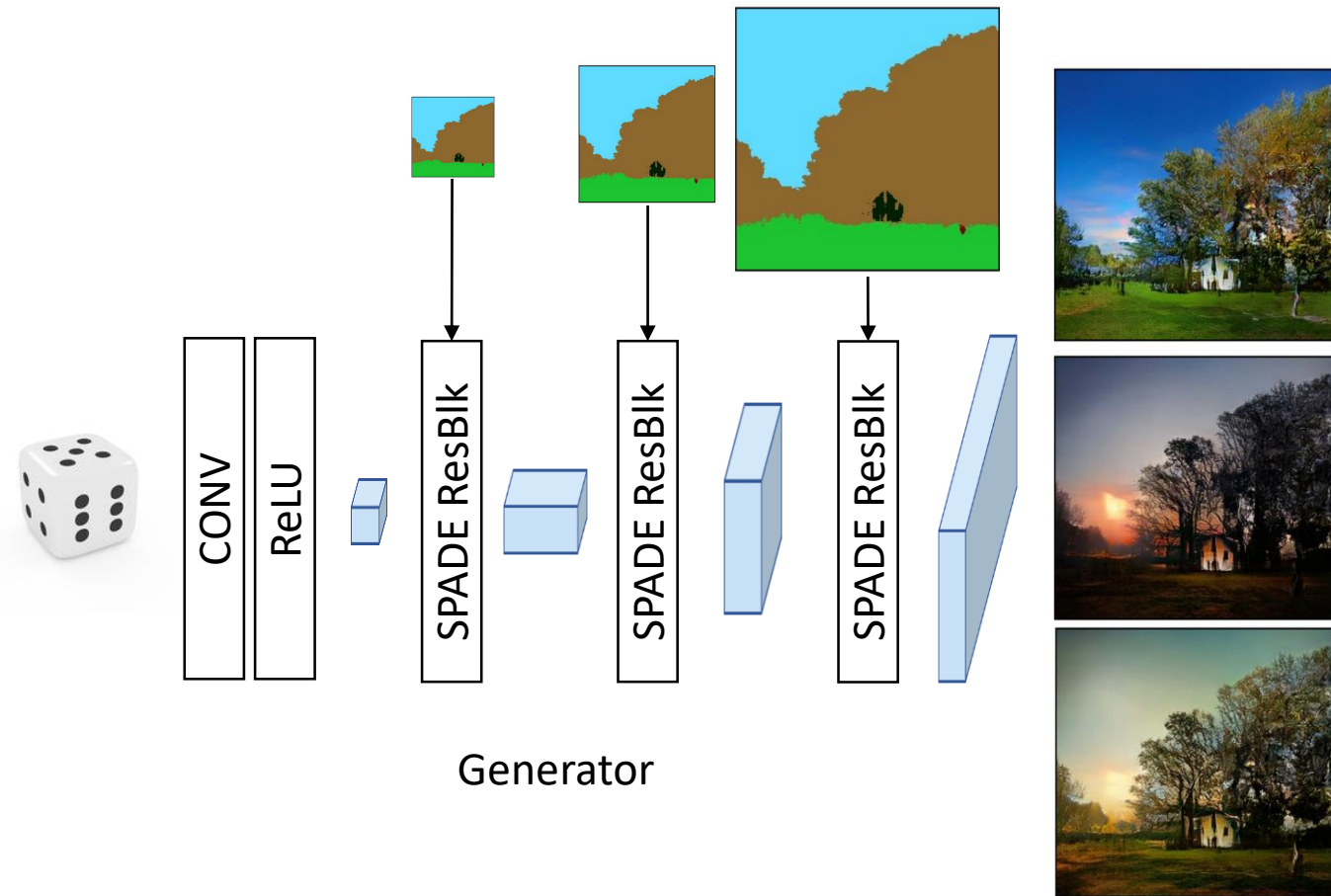
Style Control Learning via a Variational Learning Framework



Style Control Learning via a Variational Learning Framework



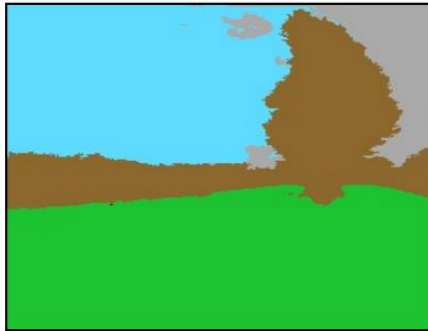
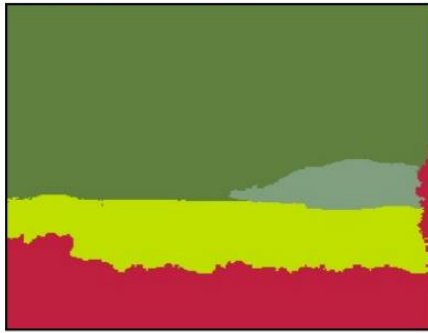
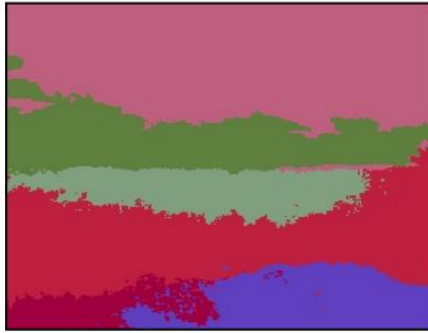
Style Control Learning via a Variational Learning Framework



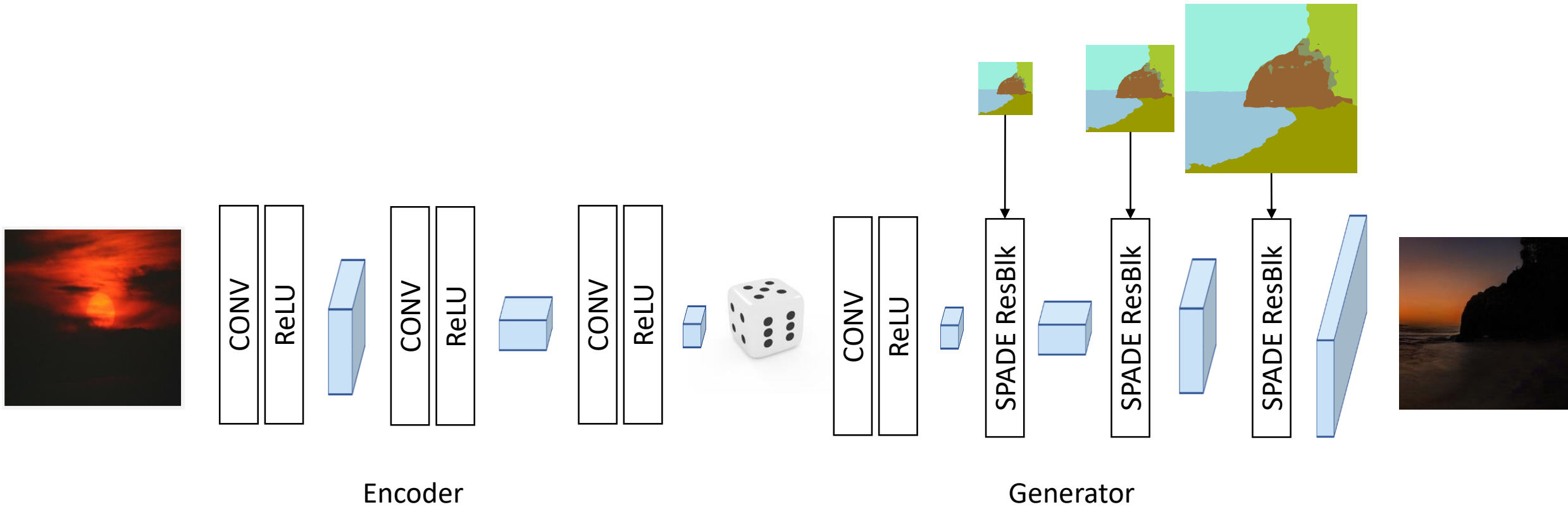
Label

Ground Truth

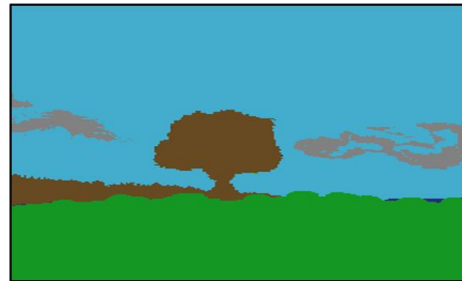
Multi-modal results



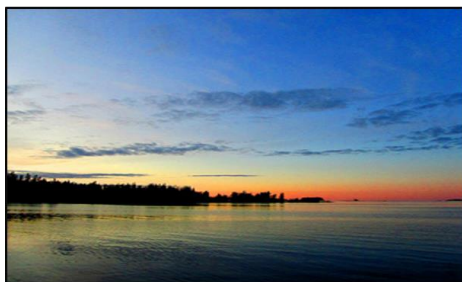
In the test time, we can then use different style images to control the global color tone of the output image.



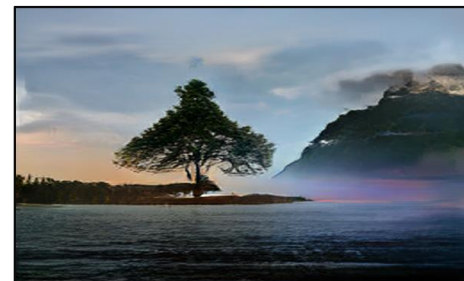
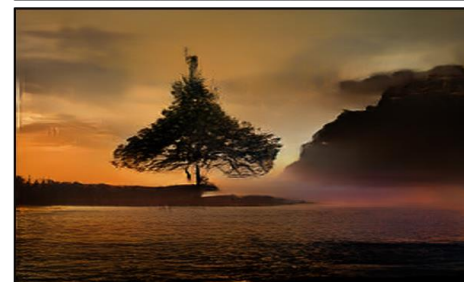
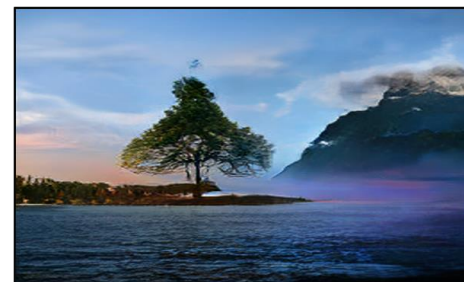
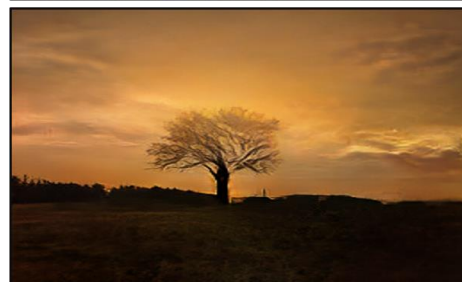
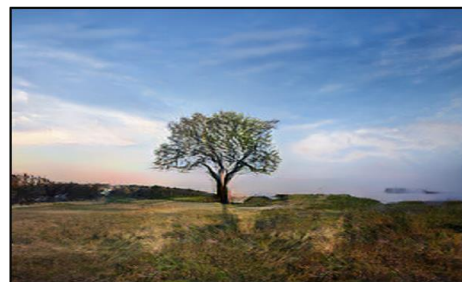
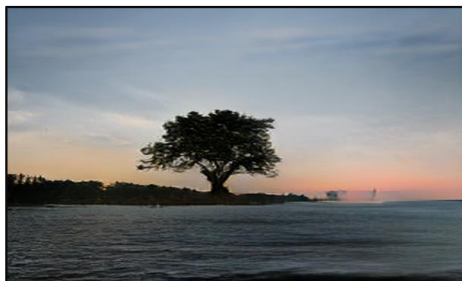
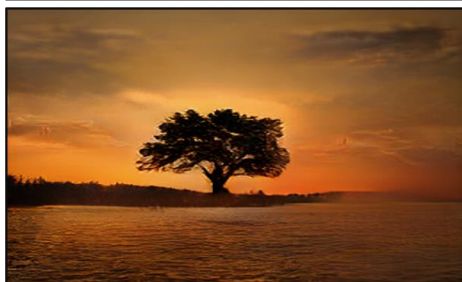
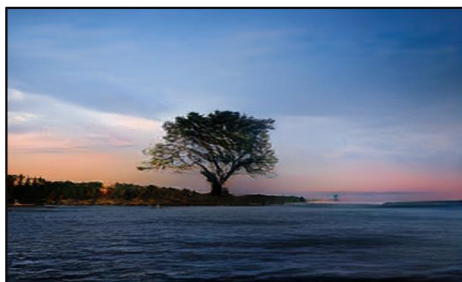
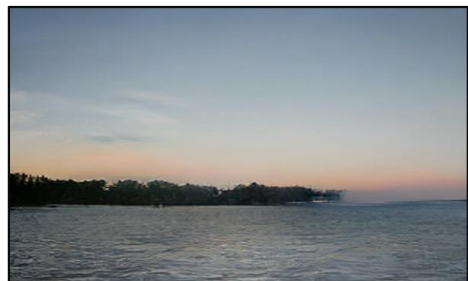
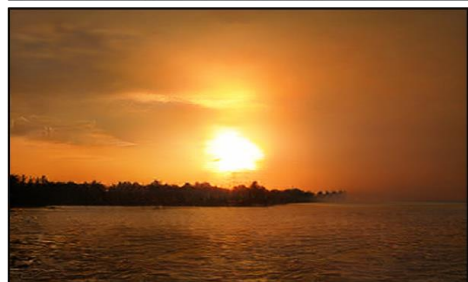
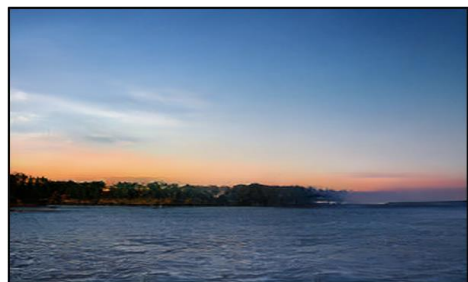
cloud	sky
tree	mountain
sea	grass



Semantic Manipulation Using Segmentation Map



Stylization using Guide Images



Conclusion

- Segmentation to Image Synthesis Task
- SPADE: Spatially Adaptive Denormalization
- Joint Style and Layout Control
- CVPR2019
- Online demo link: <http://nvidia-research-mingyuliu.com/gaugan>
- SPADE code: <https://github.com/nvlabs/spade/>
- Paper: <https://arxiv.org/abs/1903.07291>



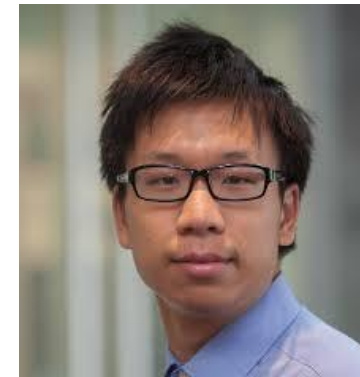
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